



**Variable frequency drive, 400 V AC, 3-phase, 4.3 A, 1.5 kW, IP20/NEMA0, 7-digital display assembly, Setpoint potentiometer, Brake chopper, STO (Safe Torque Off, SIL2, PLd Cat 3)**



**Part no. DM1-344D3NB-S20S-EM**  
**Catalog No. 3-5010-007A**

**Delivery program**

|                                    |                 |    |  |
|------------------------------------|-----------------|----|--|
| Product range                      |                 |    | Variable frequency drives  |
| Part group reference (e.g. DIL)    |                 |    | DM1  |
|                                    |                 |    |  |
| Rated operational voltage          | U <sub>e</sub>  |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase  |
| Output voltage with V <sub>e</sub> | U <sub>2</sub>  |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase  |
| Mains voltage (50/60Hz)            | U <sub>LN</sub> | V  | 380 (-10%) - 500 (+10%)  |
| <b>Rated operational current</b>   |                 |    |  |
| At 150% overload                   | I <sub>e</sub>  | A  | 4.3  |
| At 110% overload                   | I <sub>e</sub>  | A  | 5.6  |
| Note                               |                 |    | Rated operational current for a switching frequency of 1 - 16 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload                        |
| <b>Assigned motor rating</b>       |                 |    |  |
| Note                               |                 |    | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm <sup>-1</sup> at 50 Hz or 1800 min <sup>-1</sup> at 60 Hz<br>for PM motors |
| Note                               |                 |    | Overload cycle for 60 s every 600 s  |
| Note                               |                 |    | at 400 V, 50 Hz  |
| 150 % Overload                     | P               | kW | 1.5  |
| 110 % Overload                     | P               | kW | 2.2  |
| 150 % Overload                     | I <sub>M</sub>  | A  | 3.6  |
| 110 % Overload                     | I <sub>M</sub>  | A  | 5  |
| Note                               |                 |    | at 500 V, 50 Hz  |
| 150 % Overload                     | P               | kW | 2.2  |
| 110 % Overload                     | P               | kW | 3  |
| 150 % Overload                     | I <sub>M</sub>  | A  | 4  |
| 110 % Overload                     | I <sub>M</sub>  | A  | 5.3  |
| Note                               |                 |    | at 480 V, 60 Hz  |
| 150 % Overload                     | P               | HP | 2  |
| 110 % Overload                     | P               | HP | 3  |
| 150 % Overload                     | I <sub>M</sub>  | A  | 3.4  |
| 110 % Overload                     | I <sub>M</sub>  | A  | 4.8  |
| Degree of Protection               |                 |    | IP20/NEMA0   |
| Interface/field bus (built-in)     |                 |    | Modbus RTU<br>Modbus TCP<br>BACnet MS/TP<br>Ethernet IP<br>BACnet TCP  |
| Fieldbus connection (optional)     |                 |    | Profibus, CAN, DeviceNet, SmartwireDT  |
| Fitted with                        |                 |    | 7-digital display assembly<br>Setpoint potentiometer<br>Brake chopper  |
| Parameterization                   |                 |    | Keypad<br>Fieldbus<br>Power Xpert inControl  |

|                            |  |  |  |
|----------------------------|--|--|--|
| Frame size                 |  |  | FS1  |
| Connection to SmartWire-DT |  |  | yes<br>in conjunction with DXG-NET-SWD SmartWire DT module |

## Technical data

### General

|                                    |          |    |   |
|------------------------------------|----------|----|---|
| Standards                          |          |    | General requirements: IEC/EN 61800-2<br>EMV requirements: IEC/EN 61800-3<br>Safety requirements: IEC/EN 61800-5-1:2007/A1:2017; UL 61800-5-1:2012 (Rev. 2018), CSA C22.2 No. 274-17:2017  |
| Certifications                     |          |    | CE, UL, cUL, c-Tick, UkrSEPRO, EAC  |
| Production quality                 |          |    | RoHS, ISO 9001  |
| Climatic proofing                  | $\rho_w$ | %  | < 95%, average relative humidity (RH), non-condensing, non-corrosive  |
| Air quality                        |          |    | 3C2, 3S2  |
| Ambient temperature                |          |    |   |
| Operating ambient temperature min. |          | °C | -10   |
| Operating ambient temperature max. |          | °C | +50   |
| operation (110 % overload)         | $\theta$ | °C | -10 - +40 (max. +55 with 1 % derating per Kelvin temperature rise) °C   |
|                                    |          |    | Operation with 110 % overload (1 min./10 min.): -10 to +40 (max. +55 with 1% derating per Kelvin above limit)<br>Operation with 150% overload (1 min./10 min.): -10 to +50 (max. +60 with 1% derating per Kelvin above limit)<br>-20 with cold-weather mode |
| Storage                            | $\theta$ | °C | -40 - +70   |
| Overvoltage category               |          |    | III   |
| Pollution degree                   |          |    | 2   |
| Radio interference level           |          |    |   |
| Radio interference class (EMC)     |          |    | C1 (with external filter, for conducted emissions only), C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.                              |
| Environment (EMC)                  |          |    | 1st and 2nd environments as per EN 61800-3  |
| Mechanical shock resistance        |          | g  | EN 61800-5-1, EN 60068-2-6: 10 - 150 Hz<br>Amplitude: 0,75 mm (peak) bei 10 - 57 Hz<br>Maximum acceleration amplitude: 1 g at 57 – 150 Hz   |
| Mounting position                  |          |    | Vertical  |
| Altitude                           |          | m  | 0 - 1000 m above sea level<br>Above 1000 m: 1% derating for every 100 m<br>max. 3000 m (2000 m for Corner Grounded TN Systems)  |
| Degree of Protection               |          |    | IP20/NEMA0  |
| Protection against direct contact  |          |    | BGV A3 (VBG4, finger- and back-of-hand proof)   |

### Main circuit

|   |          |    |   |
|---|----------|----|---|
| Supply                                  |          |    |   |
| Rated operational voltage               | $U_e$    |    | 400 V AC, 3-phase<br>480 V AC, 3-phase<br>500 V AC, 3-phase                     |
| Mains voltage (50/60Hz)                 | $U_{LN}$ | V  | 380 (-10%) - 500 (+10%)   |
| Input current (150% overload)           | $I_{LN}$ | A  | 5.2   |
| Input current (110% overload)           | $I_{LN}$ | A  | 6.7   |
| System configuration                    |          |    | TN-S, TN-C, TN-C-S, TT, IT  |
| Supply frequency                        | $f_{LN}$ | Hz | 50/60   |
| Frequency range                         | $f_{LN}$ | Hz | 45–66 ( $\pm 0\%$ )   |
| Mains switch-on frequency               |          |    | Maximum of one time every 60 seconds  |
| Mains current distortion                | THD      | %  | 40  |
| Rated conditional short-circuit current | $I_q$    | kA | < 100   |
| Power section                           |          |    |   |
| Function                                |          |    | Variable frequency drive with internal DC link, DC link choke and IGBT inverter |
| Overload current (150% overload)        | $I_L$    | A  | 6.45  |
| Overload current (110% overload)        | $I_L$    | A  | 6.16  |
| max. starting current (High Overload)   | $I_H$    | %  | 200   |
| Note about max. starting current        |          |    | for 2 seconds every 20 seconds  |
| Output voltage with $V_e$               | $U_2$    |    | 400 V AC, 3-phase<br>480 V AC, 3-phase  |

|   |            |          |  |
|---|------------|----------|--|
|   |            |          | 500 V AC, 3-phase  |
| Output Frequency  | $f_2$      | Hz       | 0 - 50/60 (max. 400)   |
| Switching frequency   | $f_{PWM}$  | kHz      | 4<br>adjustable 1 - 16   |
| Operation Mode  |            |          | U/f control<br>Speed control with slip compensation<br>sensorless vector control (SLV)<br>Torque regulation<br>PM motors   |
| Frequency resolution (setpoint value)                       | $\Delta f$ | Hz       | 0.01   |
| Rated operational current                                   |            |          |  |
| At 150% overload  | $I_e$      | A        | 4.3  |
| At 110% overload  | $I_e$      | A        | 5.6  |
| Note  |            |          | Rated operational current for a switching frequency of 1 - 16 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload                          |
| Motor current limit   | $I$        | A        | 0.1 - 2 x $I_H$ (CT)   |
| Power loss  |            |          |  |
| Heat dissipation at rated operational current $I_e = 150\%$ | $P_V$      | W        | 62   |
| Heat dissipation at rated operational current $I_e = 110\%$ | $P_V$      | W        | 75   |
| Heat dissipation at current/speed [%]                       |            |          |  |
| Current = 100%  |            |          |  |
| Speed = 0 %   | $P_V$      | W        | 70   |
| Speed = 50 %  | $P_V$      | W        | 56   |
| Speed = 90 %  | $P_V$      | W        | 80   |
| Current = 50 %  |            |          |  |
| Speed = 0 %   | $P_V$      | W        | 71   |
| Speed = 50 %  | $P_V$      | W        | 55   |
| Speed = 90 %  | $P_V$      | W        | 57   |
| Current = 50 %  |            |          |  |
| Speed = 0 %   | $P_V$      | W        | 48   |
| Speed = 50 %  | $P_V$      | W        | 51   |
| Fan   |            |          | temperature controlled   |
| Internal fan delivery rate                                  |            | $m^3/h$  | 26   |
| Fitted with   |            |          | 7-digital display assembly<br>Setpoint potentiometer<br>Brake chopper  |
| Safety function   |            |          | STO (Safe Torque Off, SIL2, PLd Cat 3)   |
| Frame size  |            |          | FS1  |
| Motor feeder  |            |          |  |
| Note  |            |          | for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with $1500 \text{ rpm}^{-1}$ at 50 Hz or $1800 \text{ min}^{-1}$ at 60 Hz<br>for PM motors |
| Note  |            |          | Overload cycle for 60 s every 600 s  |
| Note  |            |          | at 400 V, 50 Hz  |
| 150 % Overload  | P          | kW       | 1.5  |
| 110 % Overload  | P          | kW       | 2.2  |
| Note  |            |          | at 500 V, 50 Hz  |
| 150 % Overload  | P          | kW       | 2.2  |
| 110 % Overload  | P          | kW       | 3  |
| Note  |            |          | at 480 V, 60 Hz  |
| 150 % Overload  | P          | HP       | 2  |
| 110 % Overload  | P          | HP       | 3  |
| Braking function  |            |          |  |
| Standard braking torque                                     |            |          | max. 30 % $M_N$  |
| DC braking torque   |            |          | adjustable to 150 %  |
| Braking torque with external braking resistance             |            |          | Max. 100% of rated operational current $I_e$ with external braking resistor  |
| minimum external braking resistance                         | $R_{min}$  | $\Omega$ | 105  |
| Switch-on threshold for the braking transistor              | $U_{DC}$   | V        | 800 V DC   |

|                                |                |                  |   |
|--------------------------------|----------------|------------------|---|
| DC braking                     | %              | I/I <sub>e</sub> | ≤ 150, adjustable   |
| <b>Control section</b>         |                |                  |   |
| External control voltage       | U <sub>c</sub> | V                | 24 V DC (max. 100 mA options incl.)   |
| Reference voltage              | U <sub>s</sub> | V                | 10 V DC (max. 10 mA)  |
| Analog inputs                  |                |                  | 1, can be parameterized, 0–10 V DC, 2–10 V DC, 0/4–20 mA                          |
| Analog outputs                 |                |                  | 1, parameterizable, 0 - 10 V  |
| Digital inputs                 |                |                  | 4, parameterizable, max. 30 V DC  |
| Relay outputs                  |                |                  | 2, parameterizable, 1 changeover contacts and 1 N/O, 3 A (240 VAC) / 3 A (24 VDC) |
| Interface/field bus (built-in) |                |                  | Modbus RTU<br>Modbus TCP<br>BACnet MS/TP<br>Ethernet IP<br>BACnet TCP             |
| Expansion slots                |                |                  | 1   |

### Assigned switching and protective elements

|   |  |   |  |
|---|--|---|--|
| <b>Power Wiring</b>   |  |   |  |
| Safety device (fuse or miniature circuit-breaker)                             |  |   |  |
| IEC (Type B, gG), 150 %   |  |   | PKZM0-6,3  |
| IEC (Type B, gG), 110 %   |  |   | PKZM0-6,3  |
| UL (Class CC or J)  |  | A | 10   |
| Mains contactor   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DILM7-10 (230V50HZ,240V60HZ)   |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DILM7-10 (230V50HZ,240V60HZ)   |
| Main choke  |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-LN3-006   |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DX-LN3-006   |
| Radio interference suppression filter (external, 150 %)                       |  |   | DX-EMC34-008   |
| Radio interference suppression filter (external, 110 %)                       |  |   | DX-EMC34-008   |
| Radio interference suppression filter, low leakage currents (external, 150 %) |  |   | DX-EMC34-008-L   |
| Radio interference suppression filter, low leakage currents (external, 110 %) |  |   | DX-EMC34-008-L   |
| Note regarding radio interference suppression filter                          |  |   | Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments   |
| <b>DC link connection</b>   |  |   |  |
| Braking resistance  |  |   |  |
| 10 % duty factor (DF)   |  |   | DX-BR150-0K5   |
| 20 % duty factor (DF)   |  |   | DX-BR150-0K5   |
| 40 % duty factor (DF)   |  |   | DX-BR150-1K1   |
| Notes concerning braking resistances:   |  |   | The brake resistors are assigned based on the maximum rated power of the variable frequency drive. Additional brake resistors and designs (e.g. different duty cycles) are available upon request. |
| <b>Motor feeder</b>   |  |   |  |
| motor choke   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-LM3-008   |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DX-LM3-008   |
| Sine filter   |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-SIN3-010  |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DX-SIN3-010  |
| All-pole sine filter  |  |   |  |
| 150 % overload (CT/I <sub>H</sub> , at 50 °C)                                 |  |   | DX-SIN3-006-A  |
| 110 % overload (VT/I <sub>L</sub> , at 40 °C)                                 |  |   | DX-SIN3-006-A  |

### Design verification as per IEC/EN 61439

|  |                  |    |     |
|--|------------------|----|-----|
| <b>Technical data for design verification</b>            |                  |    |     |
| Rated operational current for specified heat dissipation | I <sub>n</sub>   | A  | 5.6 |
| Equipment heat dissipation, current-dependent            | P <sub>vid</sub> | W  | 75  |
| Operating ambient temperature min.                       |                  | °C | -10 |
| Operating ambient temperature max.                       |                  | °C | 50  |

|  |  |  |
|--|--|--|
| IEC/EN 61439 design verification   |  |  |
| 10.2 Strength of materials and parts   |  |  |
| 10.2.2 Corrosion resistance  |  | Meets the product standard's requirements.   |
| 10.2.3.1 Verification of thermal stability of enclosures   |  | Meets the product standard's requirements.   |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat   |  | Meets the product standard's requirements.   |
| 10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects |  | Meets the product standard's requirements.   |
| 10.2.4 Resistance to ultra-violet (UV) radiation   |  | Meets the product standard's requirements.   |
| 10.2.5 Lifting   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.2.6 Mechanical impact   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.2.7 Inscriptions  |  | Meets the product standard's requirements.   |
| 10.3 Degree of protection of ASSEMBLIES  |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.4 Clearances and creepage distances   |  | Meets the product standard's requirements.   |
| 10.5 Protection against electric shock   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.6 Incorporation of switching devices and components   |  | Does not apply, since the entire switchgear needs to be evaluated.   |
| 10.7 Internal electrical circuits and connections  |  | Is the panel builder's responsibility.   |
| 10.8 Connections for external conductors   |  | Is the panel builder's responsibility.   |
| 10.9 Insulation properties   |  |  |
| 10.9.2 Power-frequency electric strength   |  | Is the panel builder's responsibility.   |
| 10.9.3 Impulse withstand voltage   |  | Is the panel builder's responsibility.   |
| 10.9.4 Testing of enclosures made of insulating material   |  | Is the panel builder's responsibility.   |
| 10.10 Temperature rise   |  | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 Short-circuit rating   |  | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.12 Electromagnetic compatibility  |  | Is the panel builder's responsibility. The specifications for the switchgear must be observed.                                   |
| 10.13 Mechanical function  |  | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.                         |

## Technical data ETIM 7.0

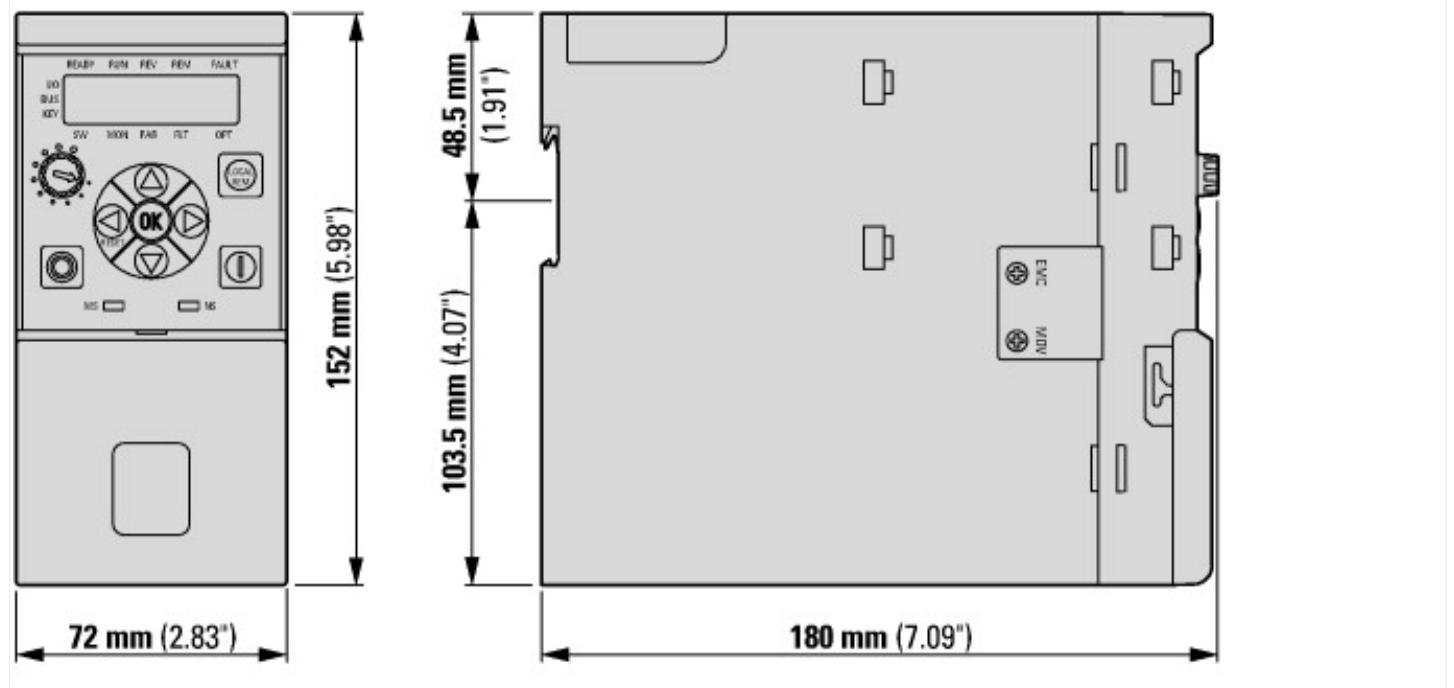
|  |    |  |           |
|--|----|--|-----------|
| Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV (EC001857)  |    |  |           |
| Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014]) |    |  |           |
| Mains voltage  | V  |  | 323 - 528 |
| Mains frequency  |    |  | 50/60 Hz  |
| Number of phases input   |    |  | 3         |
| Number of phases output  |    |  | 3         |
| Max. output frequency  | Hz |  | 400       |
| Max. output voltage  | V  |  | 500       |
| Nominal output current I2N   | A  |  | 5.6       |
| Max. output at quadratic load at rated output voltage  | kW |  | 2.2       |
| Max. output at linear load at rated output voltage   | kW |  | 1.5       |
| Relative symmetric net frequency tolerance   | %  |  | 10        |
| Relative symmetric net voltage tolerance   | %  |  | 10        |
| Number of analogue outputs   |    |  | 1         |
| Number of analogue inputs  |    |  | 1         |
| Number of digital outputs  |    |  | 0         |
| Number of digital inputs   |    |  | 4         |
| With control unit  |    |  | Yes       |
| Application in industrial area permitted   |    |  | Yes       |
| Application in domestic- and commercial area permitted   |    |  | No        |
| Supporting protocol for TCP/IP   |    |  | Yes       |
| Supporting protocol for PROFIBUS   |    |  | Yes       |
| Supporting protocol for CAN  |    |  | Yes       |
| Supporting protocol for INTERBUS   |    |  | No        |
| Supporting protocol for ASI  |    |  | No        |
| Supporting protocol for KNX  |    |  | No        |

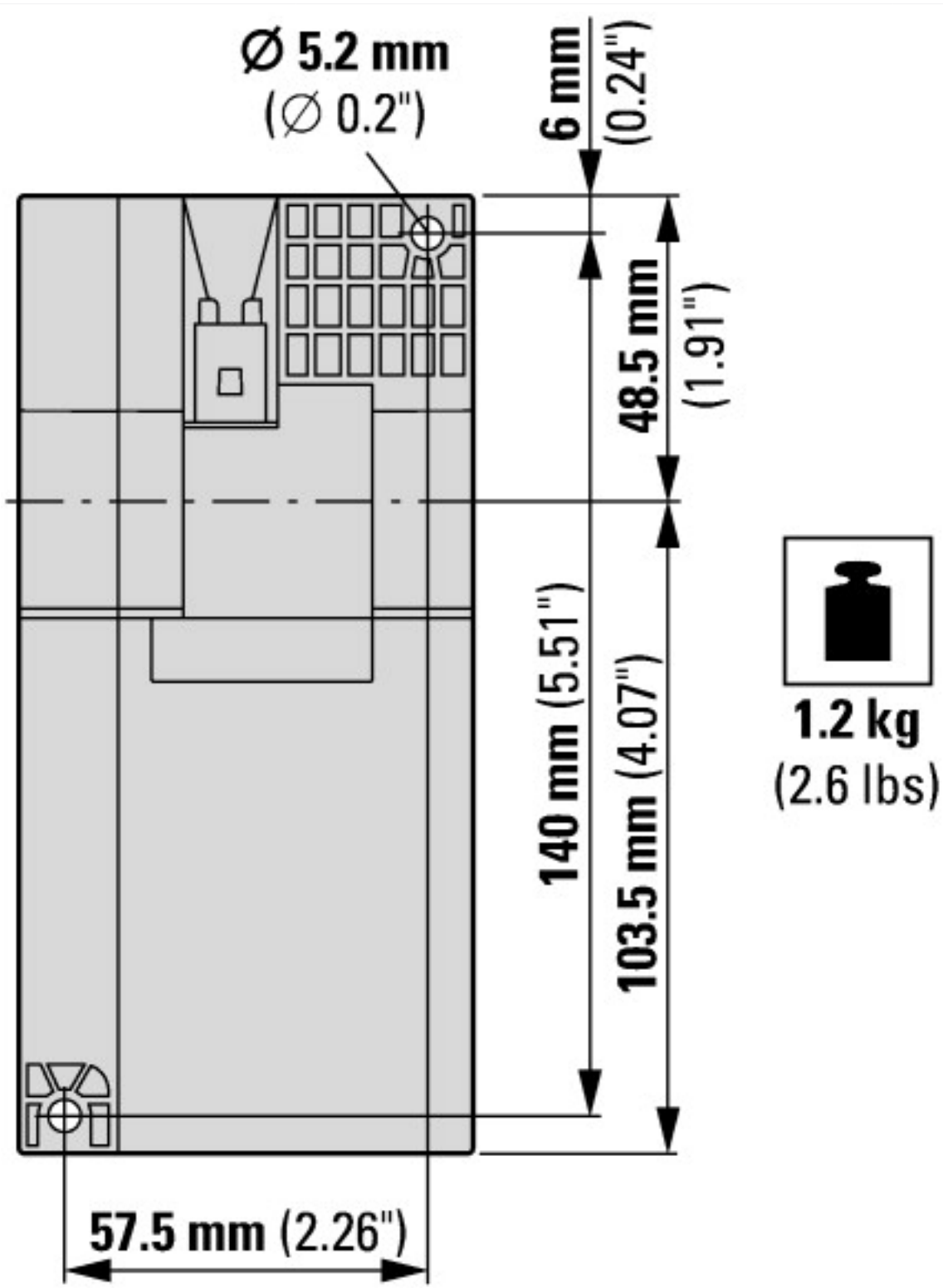
|   |    |             |
|---|----|-------------|
| Supporting protocol for MODBUS                      |    | Yes         |
| Supporting protocol for Data-Highway                |    | No          |
| Supporting protocol for DeviceNet                   |    | Yes         |
| Supporting protocol for SUCONET                     |    | No          |
| Supporting protocol for LON                         |    | No          |
| Supporting protocol for PROFINET IO                 |    | No          |
| Supporting protocol for PROFINET CBA                |    | No          |
| Supporting protocol for SERCOS                      |    | No          |
| Supporting protocol for Foundation Fieldbus         |    | No          |
| Supporting protocol for EtherNet/IP                 |    | Yes         |
| Supporting protocol for AS-Interface Safety at Work |    | No          |
| Supporting protocol for DeviceNet Safety            |    | No          |
| Supporting protocol for INTERBUS-Safety             |    | No          |
| Supporting protocol for PROFIsafe                   |    | No          |
| Supporting protocol for SafetyBUS p                 |    | No          |
| Supporting protocol for BACnet                      |    | Yes         |
| Supporting protocol for other bus systems           |    | Yes         |
| Number of HW-interfaces industrial Ethernet         |    | 1           |
| Number of interfaces PROFINET                       |    | 0           |
| Number of HW-interfaces RS-232                      |    | 0           |
| Number of HW-interfaces RS-422                      |    | 0           |
| Number of HW-interfaces RS-485                      |    | 1           |
| Number of HW-interfaces serial TTY                  |    | 0           |
| Number of HW-interfaces USB                         |    | 0           |
| Number of HW-interfaces parallel                    |    | 0           |
| Number of HW-interfaces other                       |    | 1           |
| With optical interface                              |    | No          |
| With PC connection                                  |    | Yes         |
| Integrated breaking resistance                      |    | Yes         |
| 4-quadrant operation possible                       |    | Yes         |
| Type of converter                                   |    | U converter |
| Degree of protection (IP)                           |    | IP20        |
| Degree of protection (NEMA)                         |    | Other       |
| Height  | mm | 152         |
| Width   | mm | 72          |
| Depth   | mm | 180         |

## Approvals

|                             |  |  |
|-----------------------------|--|--|
| Product Standards           |  | UL508C, CSA-C22.2 No. 274-13; IEC/EN61800-3; IEC/EN61800-5; CE marking |
| UL File No.                 |  | E134360  |
| UL Category Control No.     |  | NMMS, NMMS7  |
| CSA File No.                |  | UL report applies to both US and Canada                                |
| North America Certification |  | UL listed, certified by UL for use in Canada                           |
| Suitable for                |  | Branch circuits  |
| Max. Voltage Rating         |  | 3-500 V AC IEC: TN-S UL/CSA: 'Y' (Solidly Grounded Wey)                |
| Degree of Protection        |  | IP20/NEMA0   |

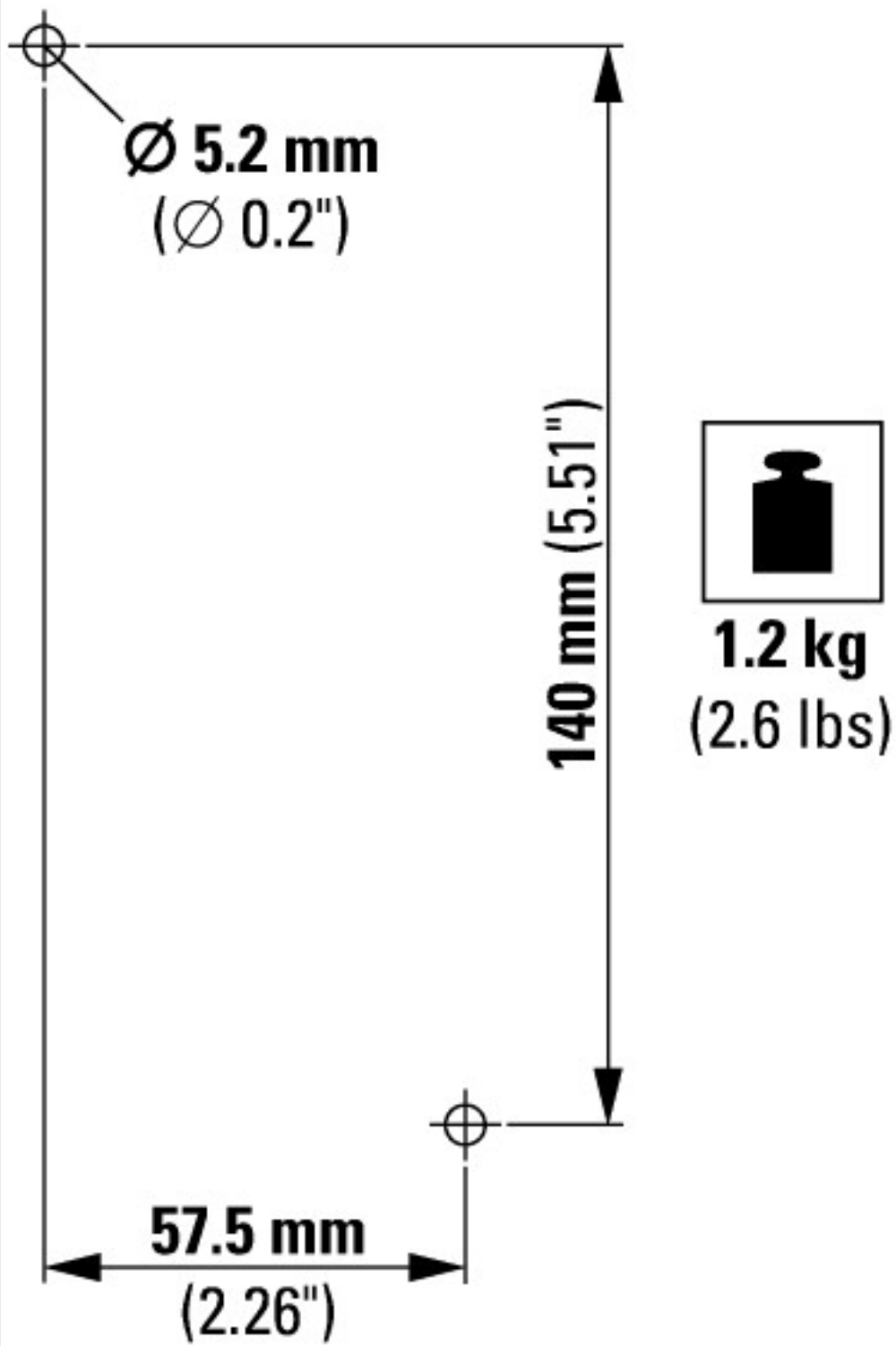
## Dimensions





Back view





Drilling patterns